

# Cordova

## Install

Install nodejs and npm

```
sudo apt-get install nodejs npm
```

Install cordova

```
sudo npm install -g cordova
```

cordova need node and ubuntu install nodejs

```
sudo ln -s /usr/bin/nodejs /usr/local/bin/node
```

install cordova-browser from git to have linux support

```
sudo npm install -g git://git.apache.org/cordova-browser.git
```

## Update

```
sudo npm update -g
```

## Install Android SDK

Create /etc/profile.d/android.sh or add in .bash\_profile

```
export ANDROID_HOME=/lab/android-sdk-linux/  
export PATH=$PATH:$ANDROID_HOME/tools:$ANDROID_HOME/platform-tools
```

## Project

### Create project

```
cordova create /lab/peper-memory org.csgalileo.peper.memory PeperMemory
```

Add android support

```
cd /lab/peper-memory  
cordova platform list
```

```
cordova platforms add android
cordova platforms add browser

# temporary patch
# cp /usr/local/lib/node_modules/cordova-
browser/bin/templates/project/cordova/run ./platforms/browser/cordova/run
```

Add to platforms/browser/cordova/run

```
case 'linux':
    spawn('chromium-browser', ['--test-type', '--disable-web-security', '-
-user-data-dir=/tmp/temp_chrome_user_data_dir_for_cordova_browser',
project]);
    break;
```

## Crosswalk

Optionally it is possible to use crosswalk instead of android webview

Add android platform to project

```
cordova platforms add android
```

Download [<https://crosswalk-project.org/documentation/downloads.html>|crosswalk]

```
CROSSWALK=/lab/crosswalk/crosswalk-cordova-10.39.235.15-arm
rm -fR platforms/android/CordovaLib/*
cp -a ${CROSSWALK}/framework/* platforms/android/CordovaLib/
cp -a ${CROSSWALK}/VERSION platforms/android/
```

Add to platforms/android/AndroidManifest.xml

```
<uses-permission android:name="android.permission.ACCESS_WIFI_STATE" />
<uses-permission android:name="android.permission.ACCESS_NETWORK_STATE" />
```

Build both the CordovaLib and xwalk\_core\_library

```
cd platforms/android/CordovaLib/
android update project --subprojects --path . --target "android-19"
ant clean debug

cd .. # platforms/android/
rm -Rf ant-gen
rm -Rf ant-build
cd ../..
cordova build android
```

## Manage project

View project detail

```
cordova info
```

Add plugins

```
cordova plugin add org.apache.cordova.device
cordova plugin add org.apache.cordova.console

# cordova plugin add https://github.com/donaldp24/CanvasCameraPlugin.git &&
cordova prepare
```

Search plugins

```
cordova plugin search <text>
```

Update corbova inside project

```
cordova platform update android
```

## Test project

```
cordova emulate browser
```

## Release

```
cordova build --release android
```

[<http://developer.android.com/tools/publishing/app-signing.html> sign and align]

## Video autoplay

Con ionic-crosswalk i video partono da soli con il set di src via javascript

```
if (! $('#video1')[0].src) {
  $('#video1')[0].src = "http://...";
}
$('#video1')[0].currentTime = 0; // rewind
$('#video1')[0].play();
```

## Cordova

CordovaApp.java

```
super.init();
super.appView.getSettings().setMediaPlaybackRequiresUserGesture(false);
```

## Cordova Crosswalk

```
...
super.init();
getSettings(super.appView).setMediaPlaybackRequiresUserGesture(false);
...

/* rende pubblica la API mascherata dalle nuove release di crosswalk */
private XWalkSettings getSettings(XWalkView webView)
{
    try
    {
        Method __getBridge =
XWalkView.class.getDeclaredMethod("getBridge");
        __getBridge.setAccessible(true);
        XWalkViewBridge xWalkViewBridge = null;
        xWalkViewBridge = (XWalkViewBridge)__getBridge.invoke(webView);
        XWalkSettings xWalkSettings = xWalkViewBridge.getSettings();
        return xWalkSettings;
    }
    catch (Exception e)
    {
        e.printStackTrace();
    }
    return null;
}
```

Posizionare un set di src dopo il device ready

```
$('#video1')[0].src =
"http://192.168.2.125:8000/lib/exe/fetch.php?media=contrade:pergari:pergari_
int.webm";
```

## GPIO

jni contain NDK project

```
|— Android.mk
|— gpio.c
|— gpio.h
```

## └─ jni\_gpio.c

Rebuild this project running 'ndk-build into jni folder'

Android.mk

```
LOCAL_PATH := $(call my-dir)

include $(CLEAR_VARS)
LOCAL_MODULE := gpio_test
LOCAL_SRC_FILES := gpio.c
LOCAL_LDLIBS += -llog
LOCAL_CFLAGS += -DEXEC
include $(BUILD_EXECUTABLE)

include $(CLEAR_VARS)
LOCAL_MODULE := libgpio
LOCAL_SRC_FILES := gpio.c jni_gpio.c
LOCAL_LDLIBS += -llog
include $(BUILD_SHARED_LIBRARY)
```

gpio.c

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <poll.h>
#include <fcntl.h>
#include <unistd.h>
#include <sys/stat.h>
#include <sys/types.h>

#include "gpio.h"

#define LOG_TAG "GPIO"

#ifdef EXEC
#include <android/log.h>
#define LOGD(...)
__android_log_print(ANDROID_LOG_DEBUG, LOG_TAG, __VA_ARGS__)
#else
#define LOGD(...) printf(">==< %s >==<\n", LOG_TAG), printf(__VA_ARGS__), printf("\n")
#endif

void on_new_value(int val);
int read_gpio(char *path, void (*callback)(int));

int main(int argc, char **argv){
```

```
    LOGD("Hello!\n");
#ifdef HOST
    return 0;
#endif
    if(argc == 2)
        return read_gpio(argv[1], on_new_value);
    else
        LOGD("missing argument path");

    return -1;
}

int read_gpio(char *path, void (*callback)(int)){
    int fd = open(path, O_RDONLY);
    char buf[11];
    int res = 0;

    if(fd == -1){
        perror("error opening file");
        return -1;
    }

    struct pollfd gpio_poll_fd = {
        .fd = fd,
        .events = POLLPRI,
        .revents = 0
    };

    for(;;){
        res = poll(&gpio_poll_fd,1,-1);
        if(res == -1){
            perror("error polling");
            break;
        }

        if((gpio_poll_fd.revents & POLLPRI) == POLLPRI){
            LOGD("POLLPRI");
            int off = lseek(fd, 0, SEEK_SET);
            if(off == -1) break;
            memset(&buf[0], 0, 11);
            size_t num = read(fd, &buf[0], 10*sizeof(char));
            callback(atoi(buf));
        }

        if((gpio_poll_fd.revents & POLLERR) == POLLERR){
            //seems always to be true ..
            //LOGD("POLLERR");
        }
    }
    return 0;
}
```

```
void on_new_value(int val){
    LOGD("interrupt received, val: %d", val);
}
```

gpio.h

```
#ifndef _GPIO_H_
#define _GPIO_H_
int read_gpio(char *path, void (*callback)(int));
#endif
```

jni\_gpio.c

```
#include <jni.h>
#include <stdlib.h>
/* Header for class nativehelper_NativeGpio */
#include "gpio.h"

#define LOG_TAG "GPIO"

#ifndef HOST
#include <android/log.h>
#define LOGD(...)
__android_log_print(ANDROID_LOG_DEBUG, LOG_TAG, __VA_ARGS__)
#else
#define LOGD(...) printf(">==< %s >==<\n", LOG_TAG), printf(__VA_ARGS__), printf("\n")
#endif

#ifndef _Included_nativehelper_NativeGpio
#define _Included_nativehelper_NativeGpio
#endif
#ifdef __cplusplus
extern "C" {
#endif

static void on_new_value(int val);

static jmethodID cb_method_id;
static jclass cb_class;
static jobject cb_object;
static JNIEnv *cb_save_env;

/*
 * Class:      csgalileo_NativeGpio
 * Method:     readGpio
 * Signature:  (Ljava/lang/String;Lcsgalileo/NativeGpio/GpioInterruptCallback;)V
 */
JNIEXPORT void JNICALL Java_csgalileo_NativeGpio_readGpio
(JNIEnv *env, jclass cls, jstring path, jobject callback){
```

```
cb_class = (*env)->GetObjectClass(env, callback);
if(cb_class == NULL){
    LOGD("callback interface not found");
    return;
}

cb_method_id = (*env)->GetMethodID(env, cb_class, "onNewValue", "(I)V");
if(cb_method_id == NULL){
    LOGD("could not find callback method");
    return;
}

cb_object = callback;
cb_save_env = env;

const char *fname = (*env)->GetStringUTFChars(env, path, NULL);
LOGD("path is %s", fname);
read_gpio((char *)fname, on_new_value);
(*env)->ReleaseStringUTFChars(env, path, fname);
}

static void on_new_value(int val){
    LOGD("on_new_value interrupt received, val: %d", val);
    (*cb_save_env)->CallVoidMethod(cb_save_env, cb_object, cb_method_id,
(jint)val);
}
#ifdef __cplusplus
}
#endif
```

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<https://wiki.csgalileo.org/> - Galileo Labs

Permanent link:

<https://wiki.csgalileo.org/tips/cordova>

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